

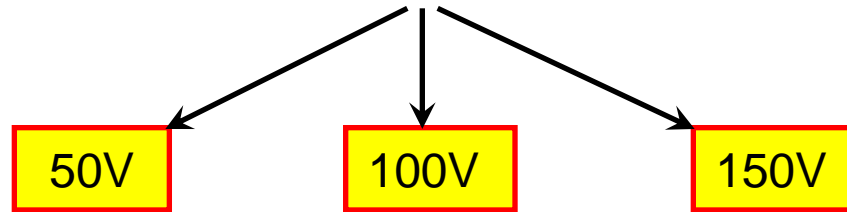
**A FAMILY OF
TWENTY-AMPERES POWER SUPPLIES
FOR MULTI-POLE CORRECTORS
FOR ACCELERATORS
AND STORAGE RINGS**

O. Belikov, V. Kozak, A. Medvedko

BINP SB RAS



TWENTY-AMPERES POWER SUPPLIES



CURRENT INSTABILITY

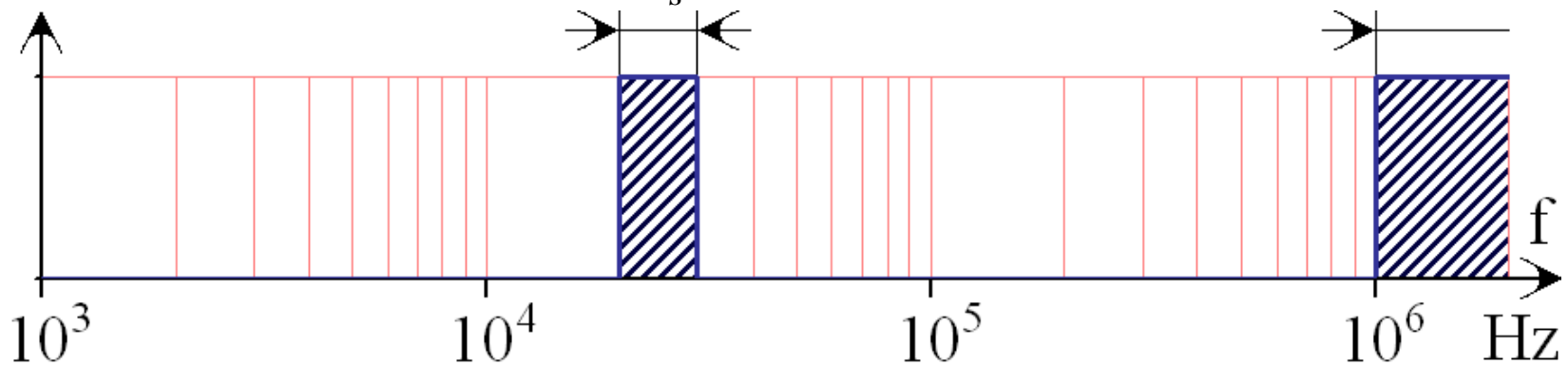
Static error: $\leq 0,1\%$

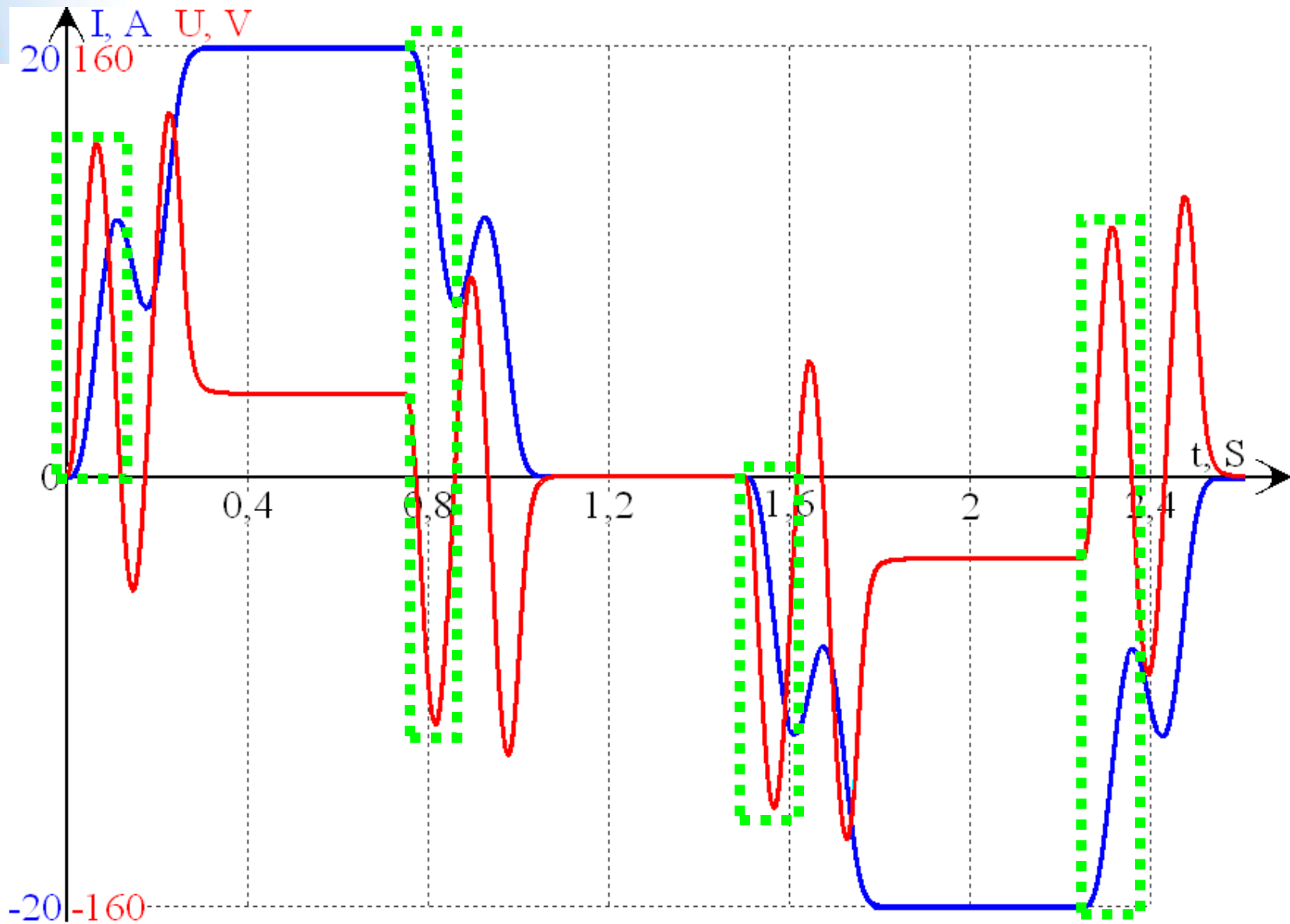
Dynamic error: $\leq 1\%$

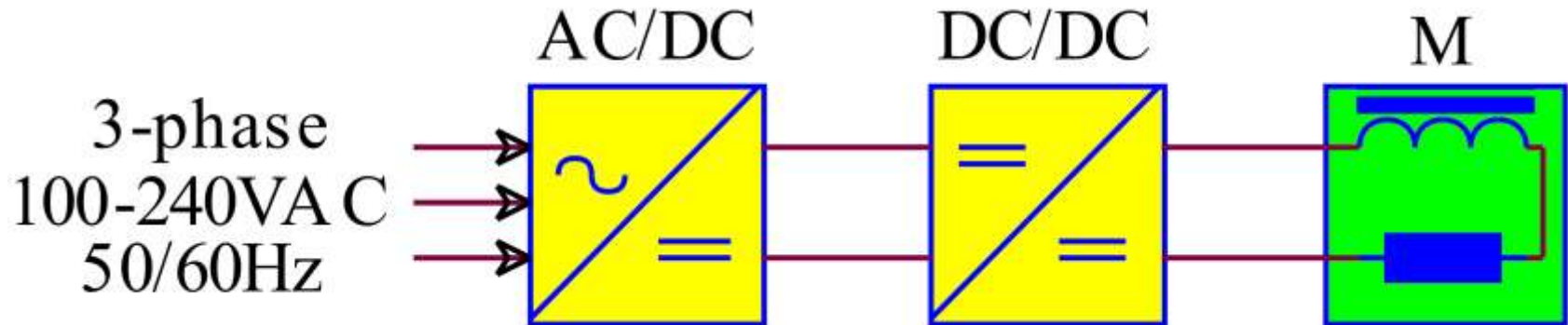
CURRENT RIPPLE

$$10\text{kHz} \leq \nu_s \leq 30\text{kHz}$$

$$Q_{x,z} \geq 1\text{MHz}$$







AC/DC – *Alternating current / Direct current and*

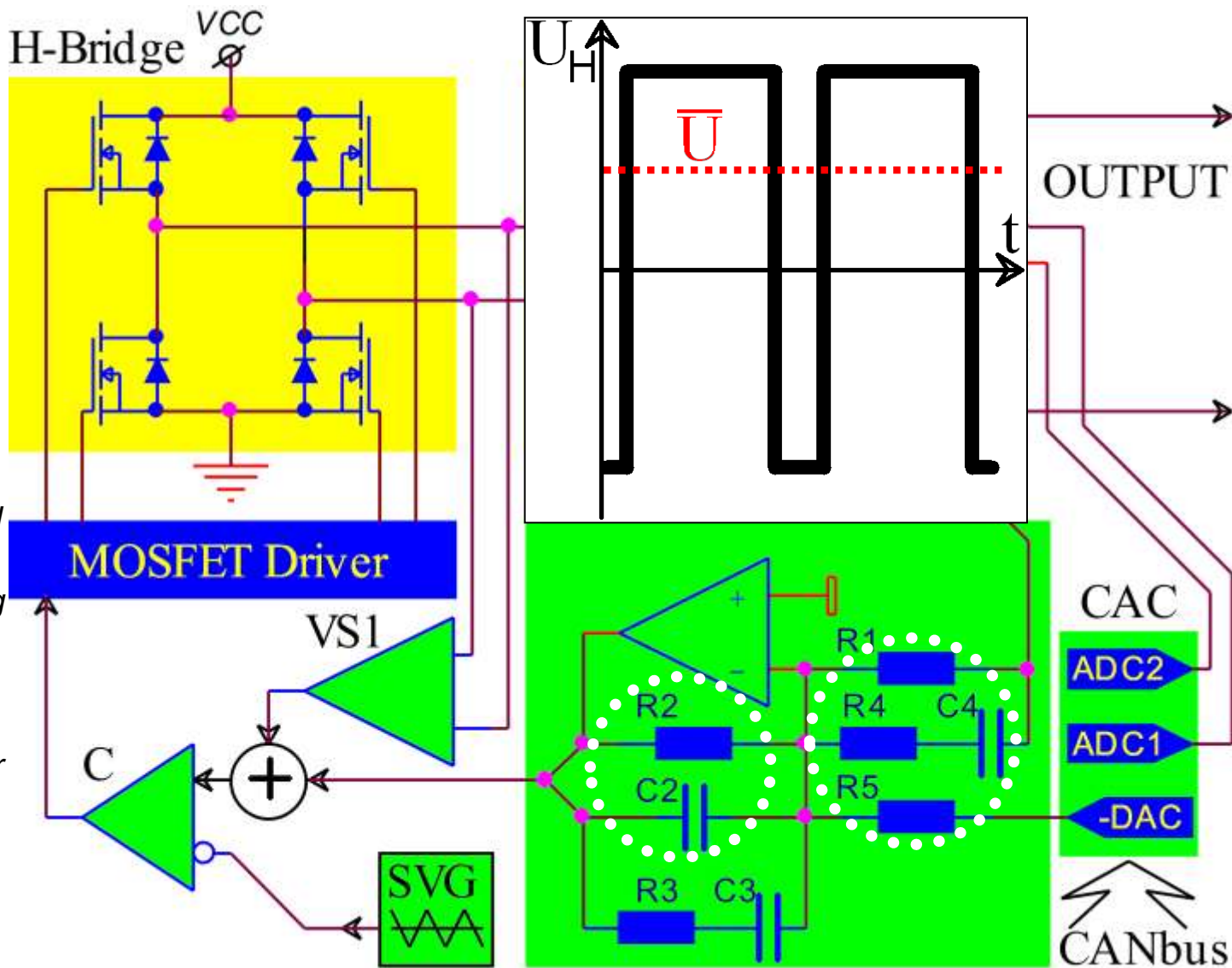
DC/DC – *Direct current / Direct current convertors*

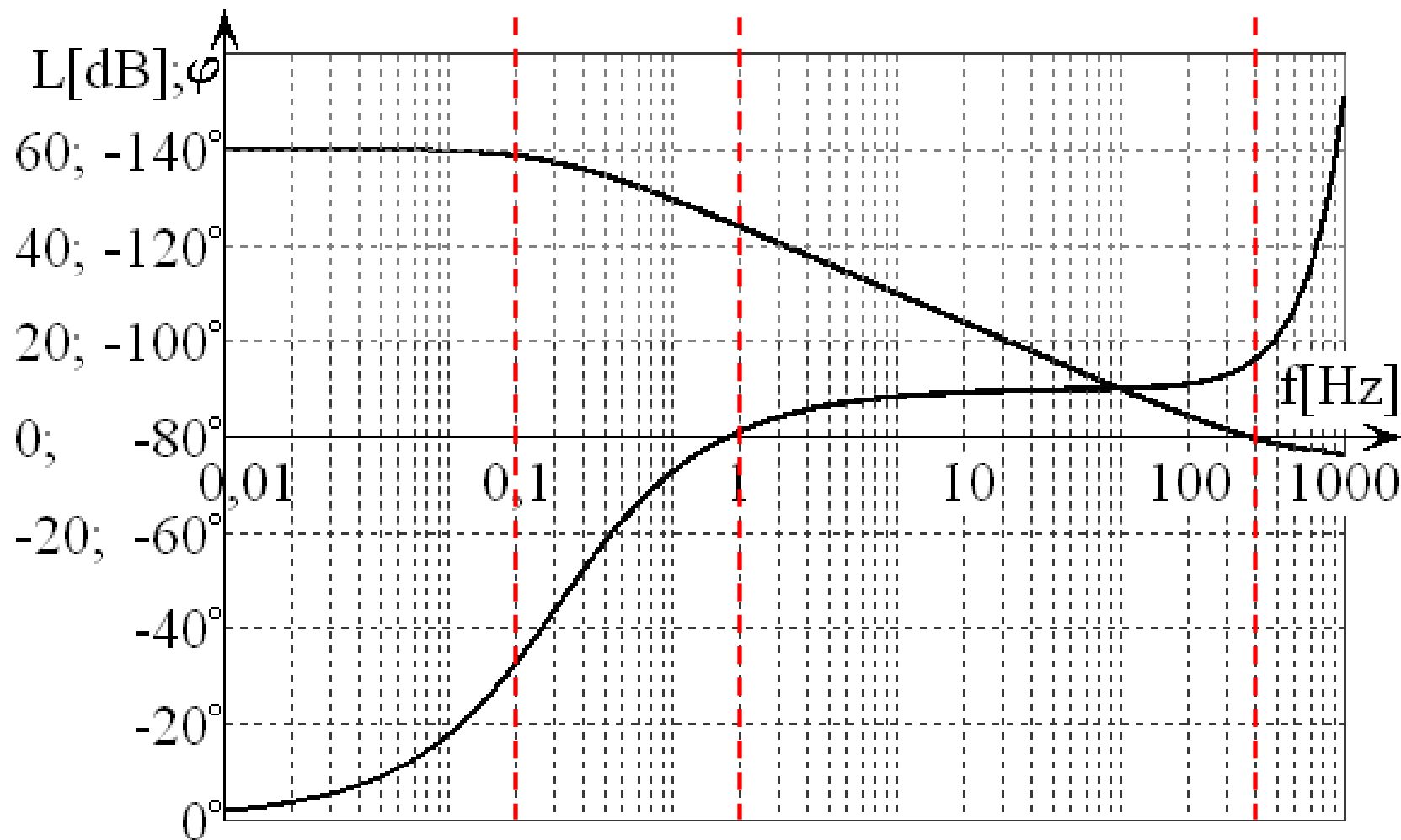
M – *Electromagnet*



CURRENT SOURCE STRUCTURE **BINP SB RAS**

- H-Bridge** – H-Bridge inverter
- LPF** – Low-pass filter
- HCS** – Hall Current Sensors
- VS** – Voltage sensor
- ESA** – Error-signal amplifier
- CAC** – Controller with the CANbus interface
- ADC** – Analog-to-digital converter
- DAC** – Digital-to-analog converter
- C** – Comparator
- SVG** – Sawtooth-voltage generator



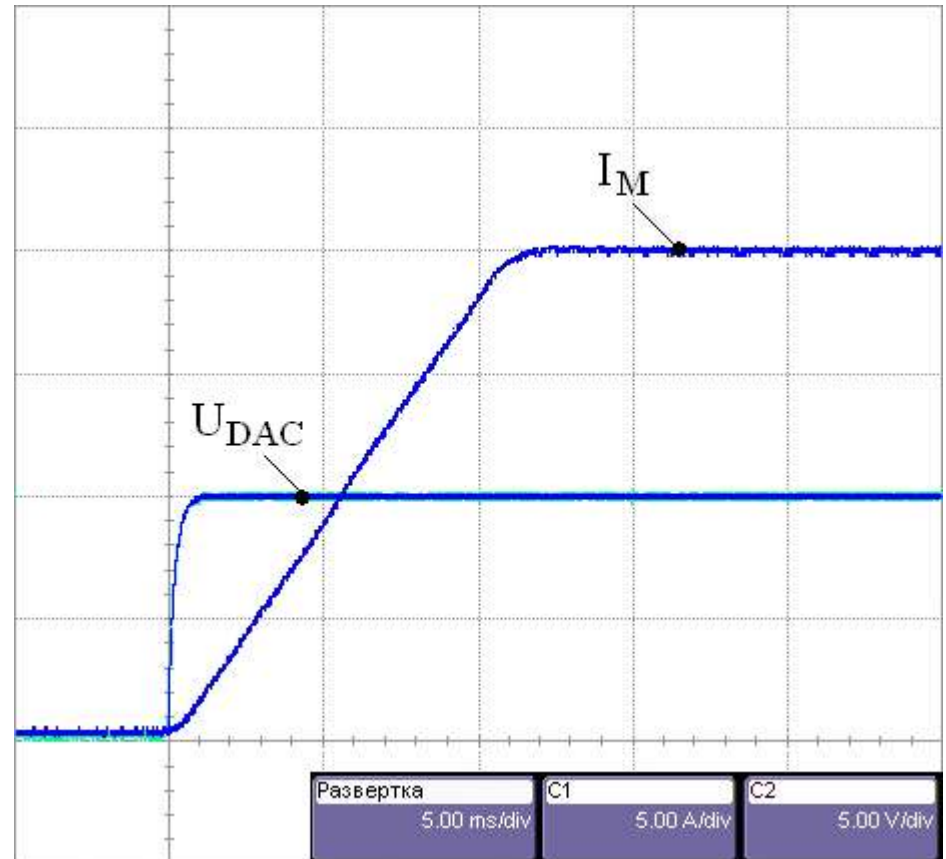


L – Gain-frequency response

φ – Phase-frequency characteristic



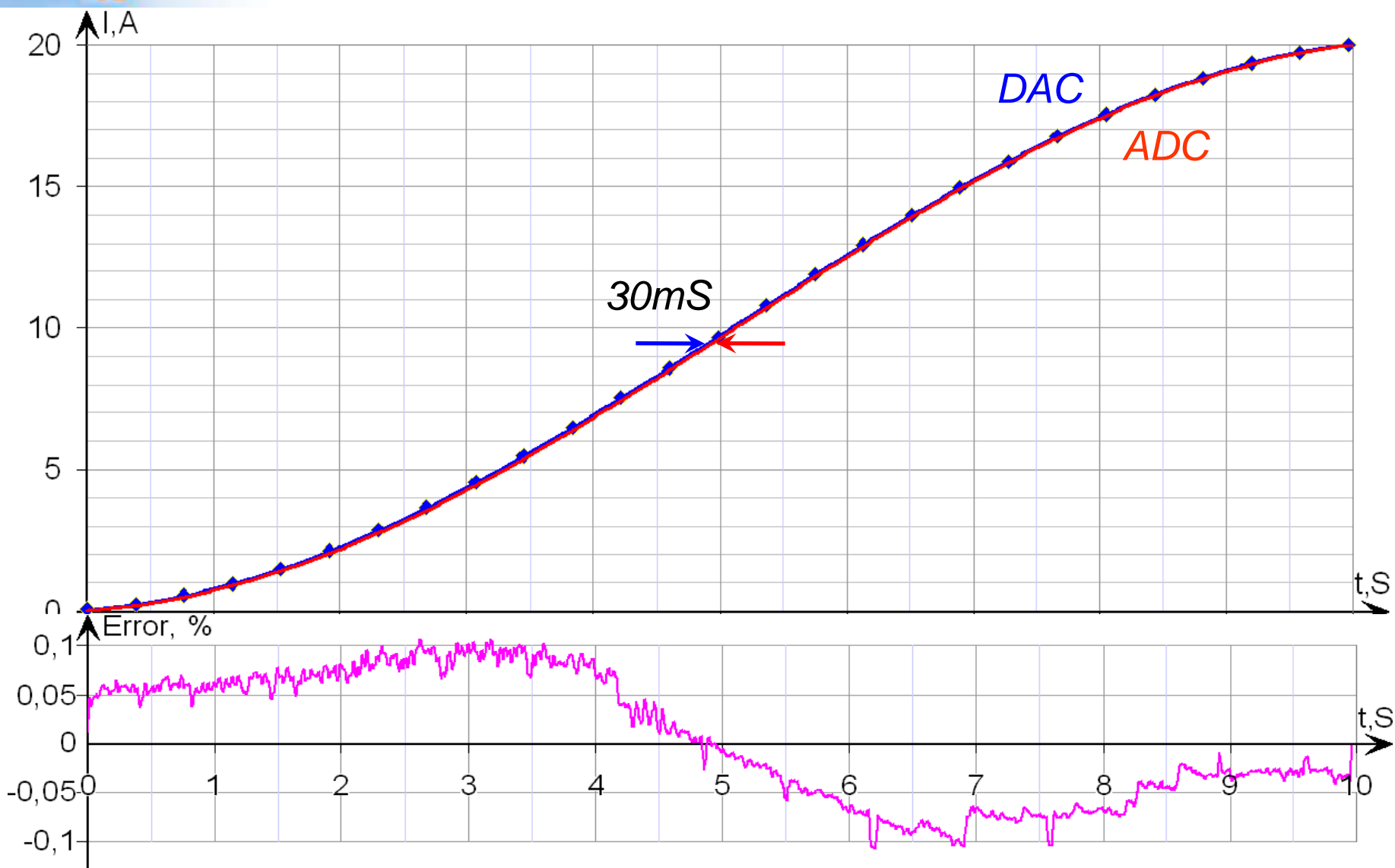
- dynamic control
- static control





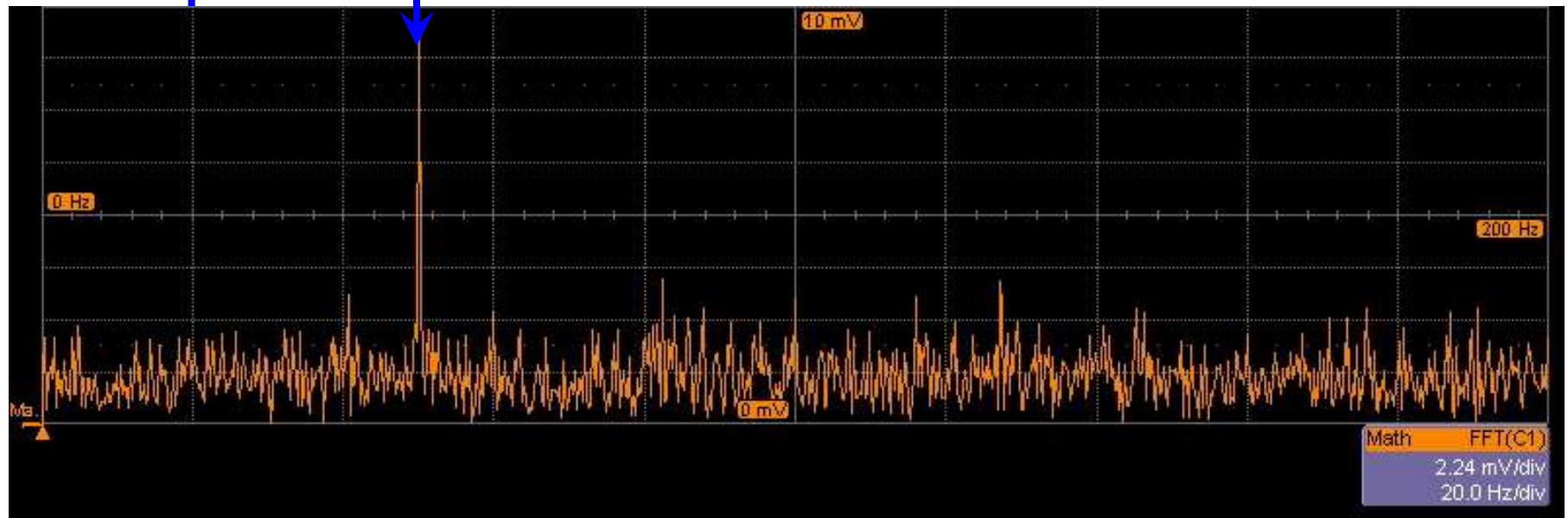
- dynamic control

(Data loading: 2 points/s)



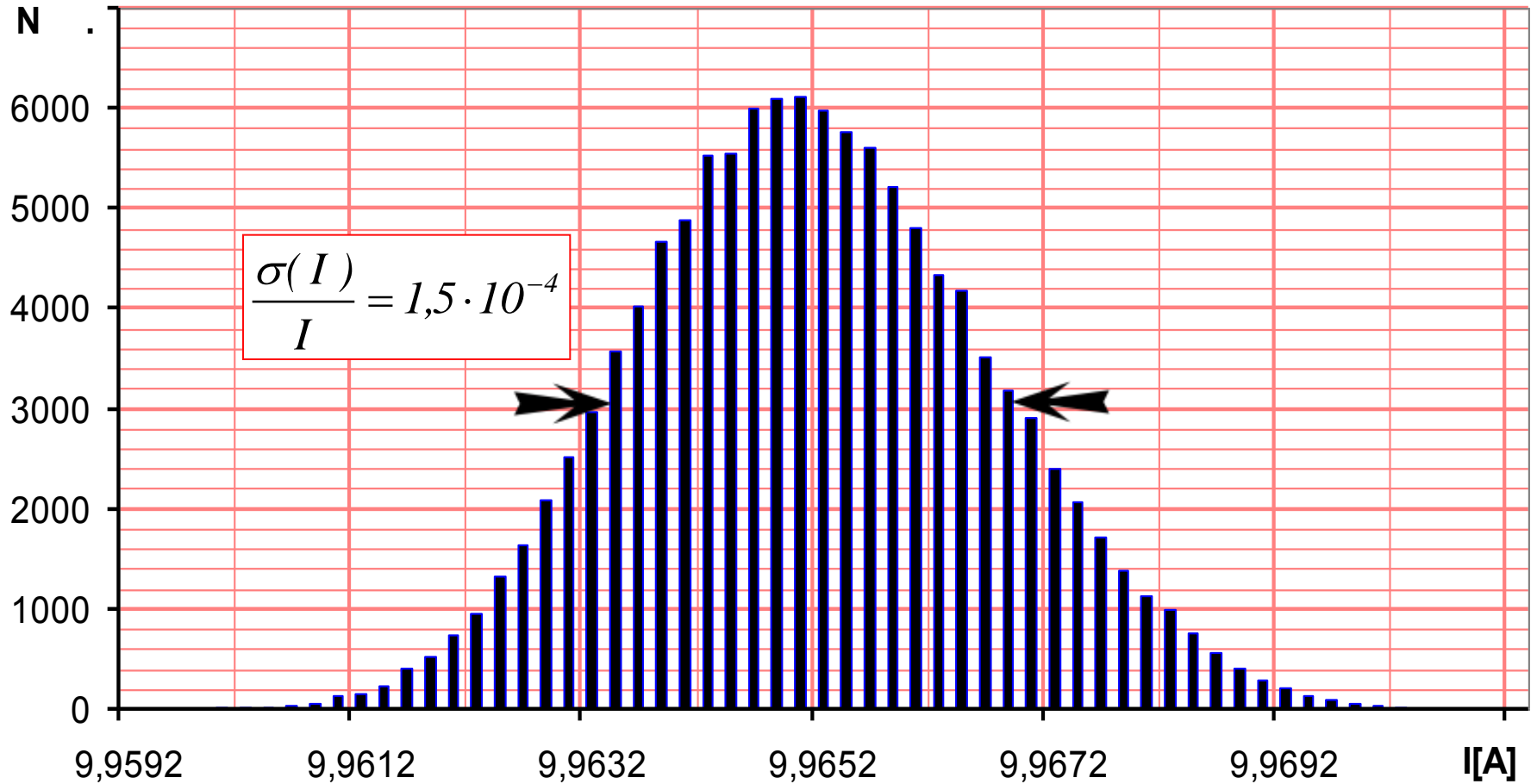


Ripple Ripple of 50Hz



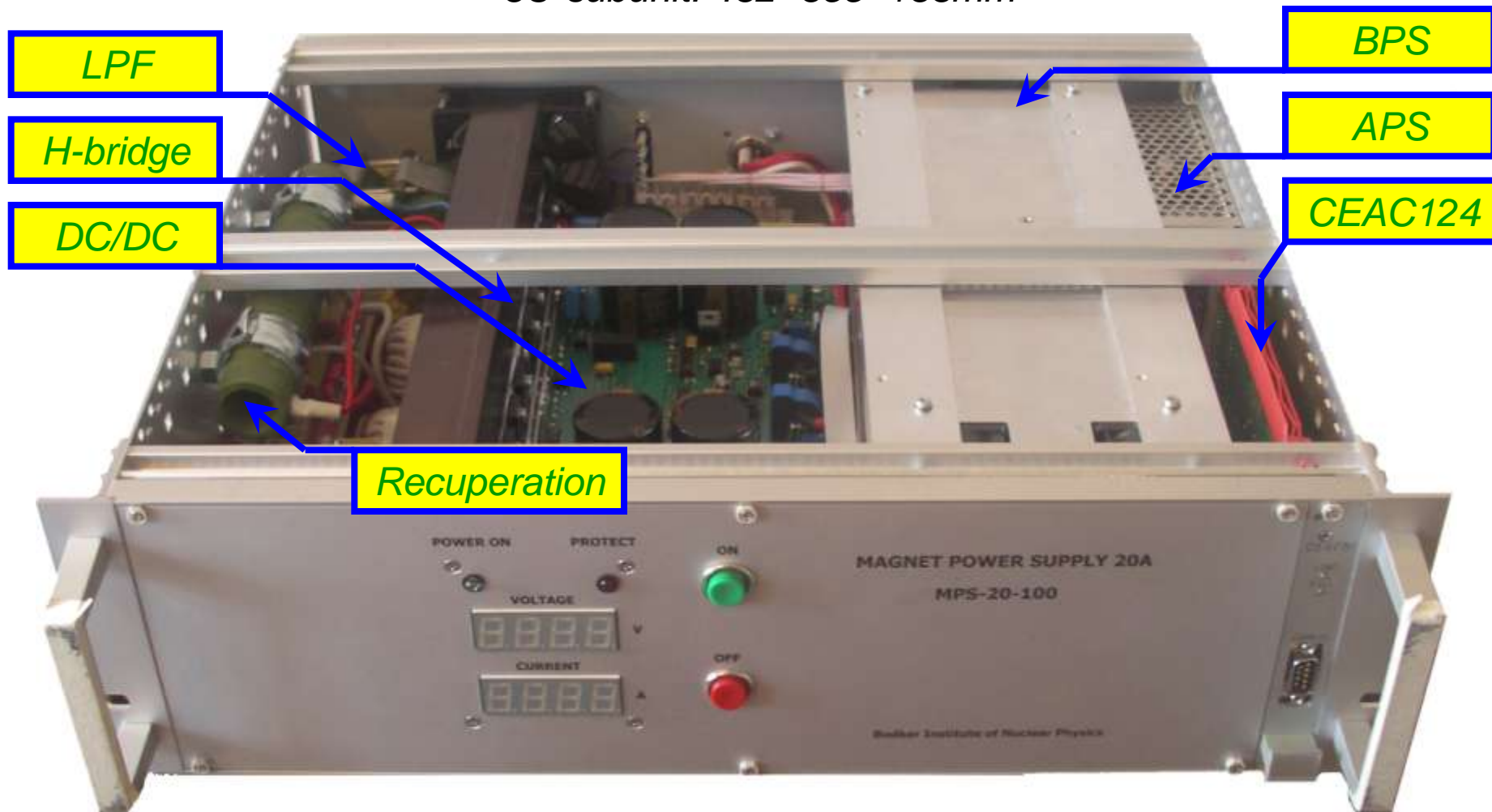


Instability / 24 hours





3U-subunit: 432×355×133mm



Mains: 220/380VAC and 120/208VAC, 50/60Hz


The control via the CANbus







Parameters		Magnet Power Supply		
I_{OUT}	Output current	$\pm 20A$		
U_{OUT}	Output voltage	MPS-20-50	MPS-20-100	MPS-20-150
		$\pm 50V$	$\pm 100V$	$\pm 150V$
f_{PWM}	Conversion frequency	50kHz		
X_G	Current accuracy	0,1% of I_{MAX}		
σ	Output current dispersion	100ppm of I_{MAX} <i>for the 10hours</i>		
TCl_{OUT}	Thermal drift of I_{OUT}	40ppm/K		
P_D	Heat loss	MPS-20-50	MPS-20-100	MPS-20-150
		$\leq 150 W$	$\leq 250 W$	$\leq 350 W$



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Thanks for your attention!