



Preliminary Engineering Design of the Central Instrumentation and Control Systems for the IFMIF-DONES Plant

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- Introduction
- Central Instrumentation and Control Systems:
general architecture
- Main components identification
- Network Design
- Conclusion and future work

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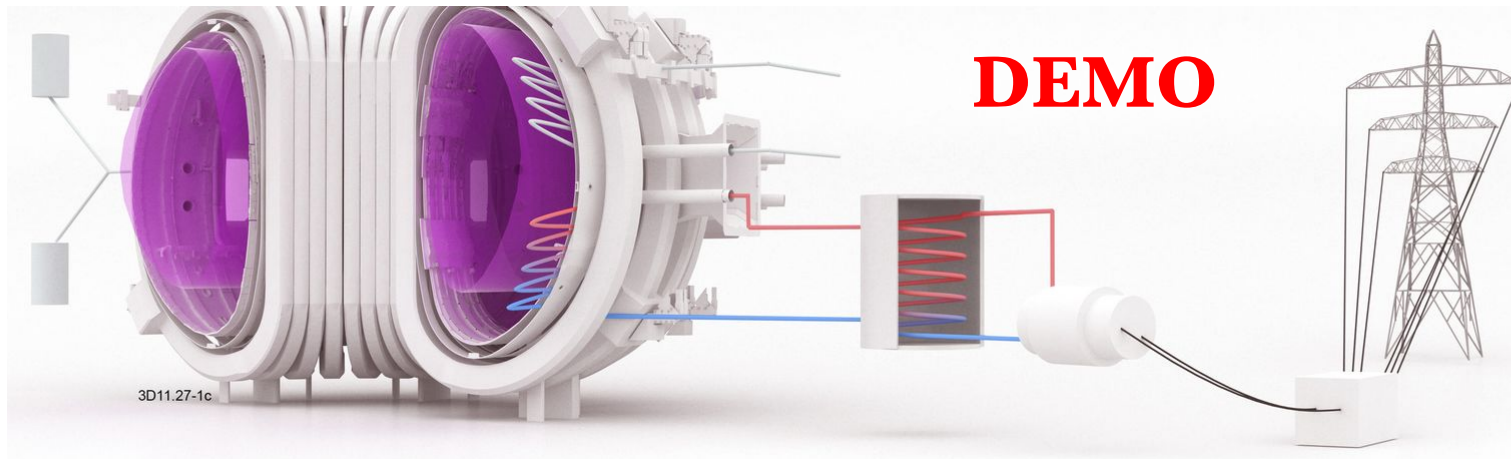


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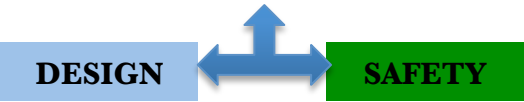




Fusion Power Plants (DEMO) are characterized by the presence of **14 MeV** fusion neutrons in the **first wall area**.



UNDERSTANDING THE DEGRADATION OF THE MATERIALS



Presently available n sources are not adequate to reproduce fusion-like environment

- **Fission reactors:**
0.3 appm He/dpa
- **Spallation sources:**
50-70 appm He/dpa, pulsed, light ions,...



A specific source for fusion neutrons is required

Consensus on an accelerator-based neutron source exploiting **D-Li stripping reactions:**
Li(d, xn)

A 40-year long history

In the '80s
FMIT (Fusion Materials Irradiation Test) in the US
deuterons at 100 mA in CW and 35 MeV for a 0.01 l volume

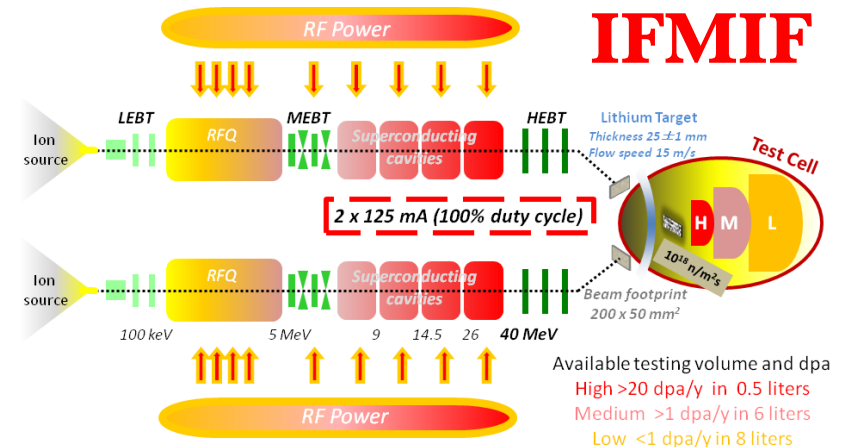
In the '90s
ESNIT (Energy Selective Neutron Irradiation Test) in Japan
deuterons at 50 mA and 40 MeV for a 0.125 l volume

Since 1994
IFMIF (International Fusion Materials Irradiation Facility)
RF, US, JA, EU joined efforts and generated a baseline

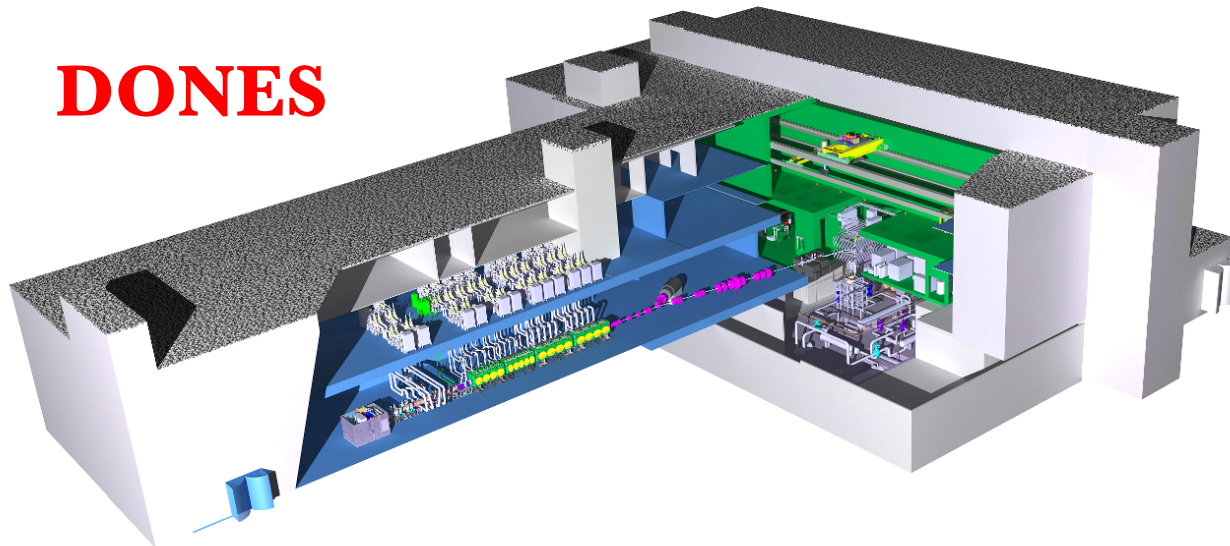
Since 2007
IFMIF/EVEDA project included in the EU-JA Broader Approach Agreement
JA, EU joined efforts

IFMIF (International Fusion Materials Irradiation Facility):

- **two** parallel deuteron accelerators
- **a neutron flux with a broad peak at 14 MeV**
- Li(d,xn) nuclear reactions: liquid Li target (20 cm x 5 cm)
- energy of the beam: **40 MeV**
- current of the parallel accelerators (2 x 125 mA)
- around 1000 small specimens



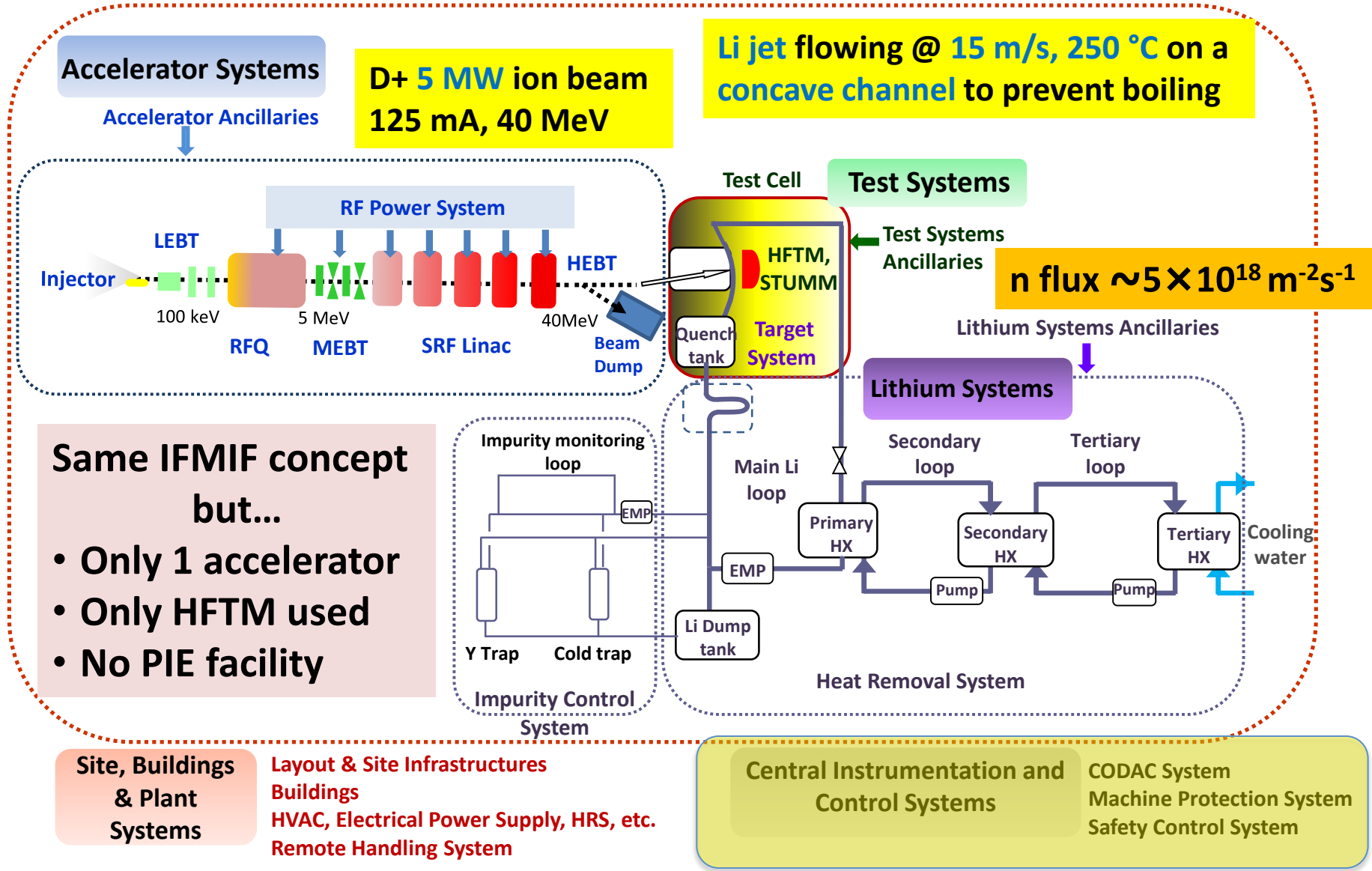
DONES



DONES (DEMO-Oriented Neutron Early Source)

Generation of materials irradiation test data for design, licensing, construction and safe operation of **DEMO**, as defined in the 2012 EU Roadmap.

- **one full IFMIF accelerator,**
- **one D+ beam of 40 MeV,**
- **current intensity 125 mA**
- **20 dpa/full power year (iron equivalent) in the materials.**



The WPENS/DONES project

IFMIF-EVEDA validation activities: EVEDA Li Test Loop (ELTL), Heloka, Lifus6, LIPAc



FUSION FOR ENERGY

IFMIF-DONES validation activities



2007 -----> 2013 2014 2015 2016 2017 2018 2019 2020

IFMIF EDR
(mid 2013)

EUROfusion WP Early Neutron Source (WPENS)

IFMIF-DONES
Conceptual Design
Report (2014)

Reference
Design (2016)

PED report
(2017)

Site Proposal
(GRANADA)

PSAR (2018)

Final Design of
Buildings & Plant
Systems (2019)

Technical Specs
of B&PS (2020)

Objectives of the WPENS project (as of EUROfusion Workprogramme):
To be ready for IFMIF/DONES construction in early 2020s

CICS main objective:
control the **high-quality irradiation** of samples in a **safe** way, avoiding any damage, and supervising and monitoring all the plant parameters for **long time**

- Ensure and maximize the operation success
- Provide full control of process and events
- Contribute to security and safety
- Guarantee protection (personal and machine)
- Guarantee functionality
- Avoid/predict accident (if any, mitigate it), misalignment/malfunctioning
- Provide monitoring & acquisition of exp. data and control parameters
- Provide operation scenarios flexibility
- Guarantee synchronization and common temporal reference

Plant operation control and supervision

Operation parameter control, visualization and monitoring

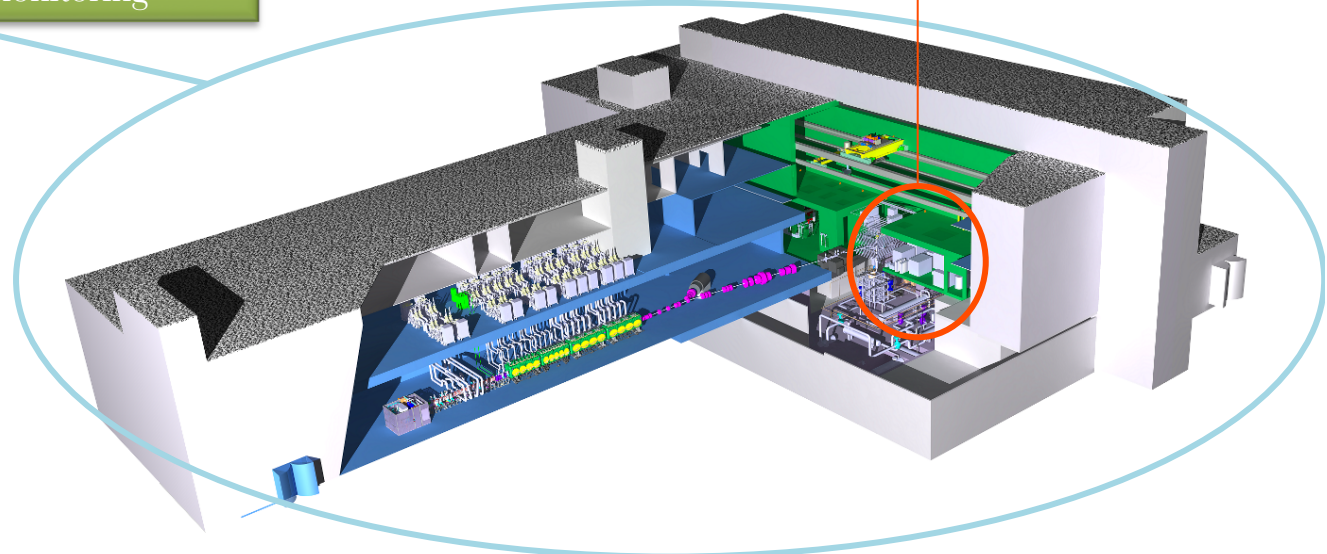
Timing & Synchronization

Irradiation and quality control

irradiation parameter, visualization and monitoring



Data monitoring and management

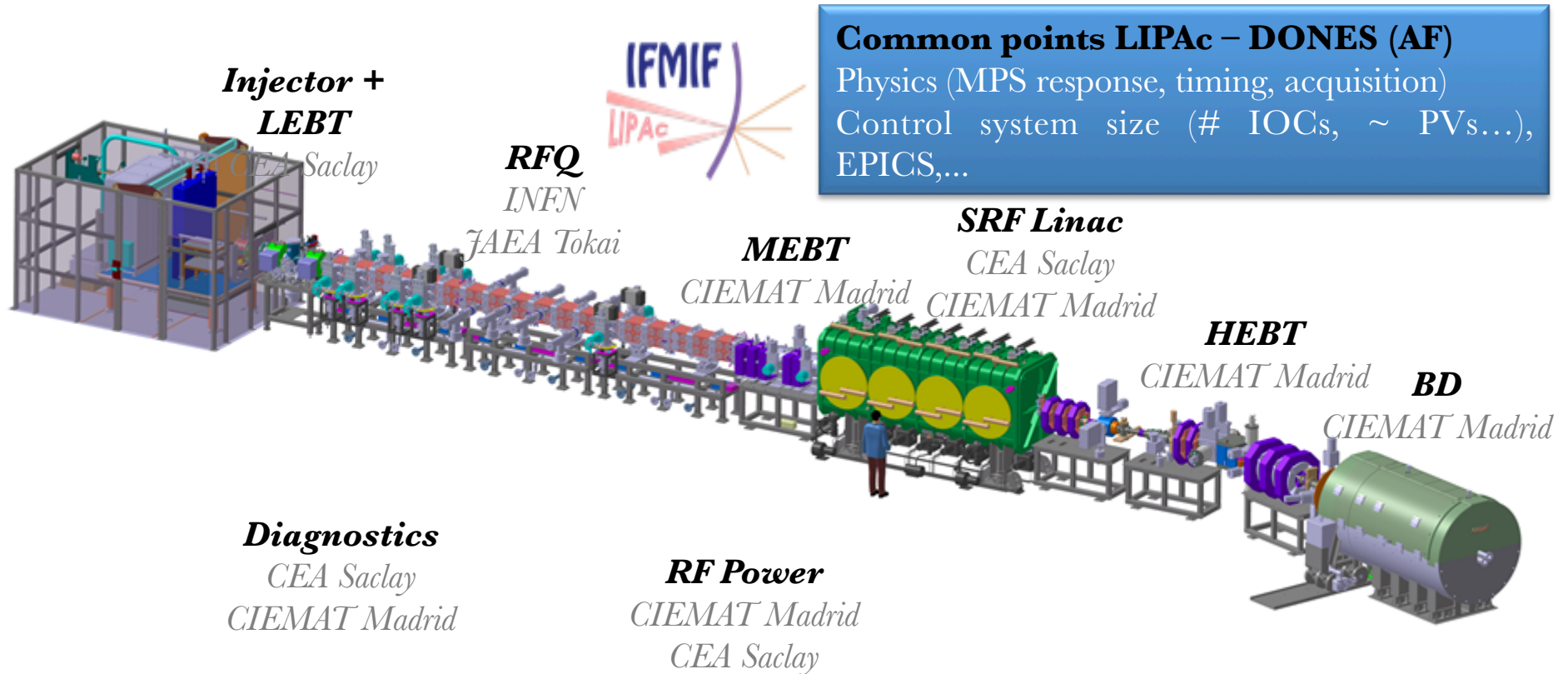




EUROPEAN SPALLATION SOURCE



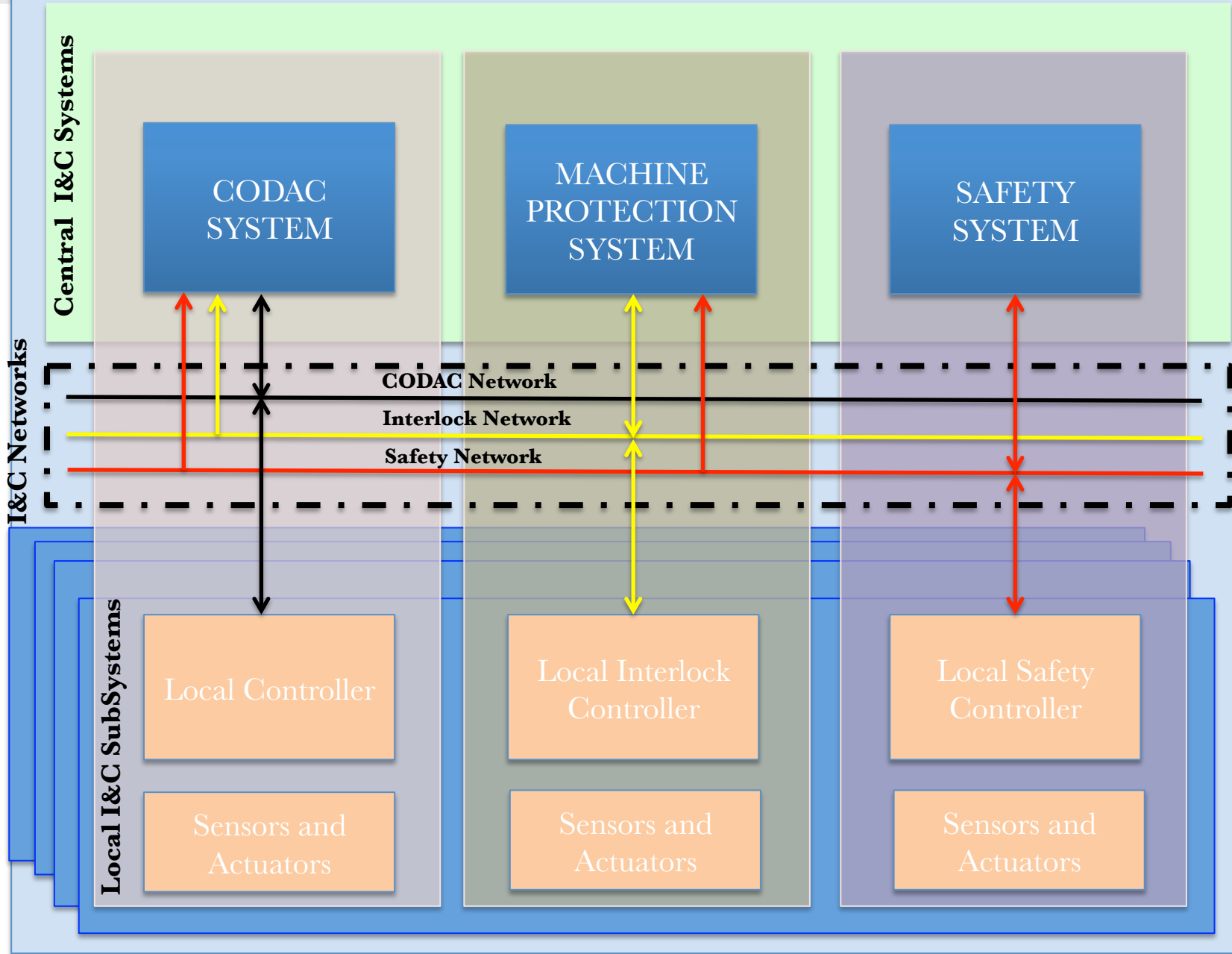
Return of experience: the LIPAc case





DONES I&C SYSTEMS

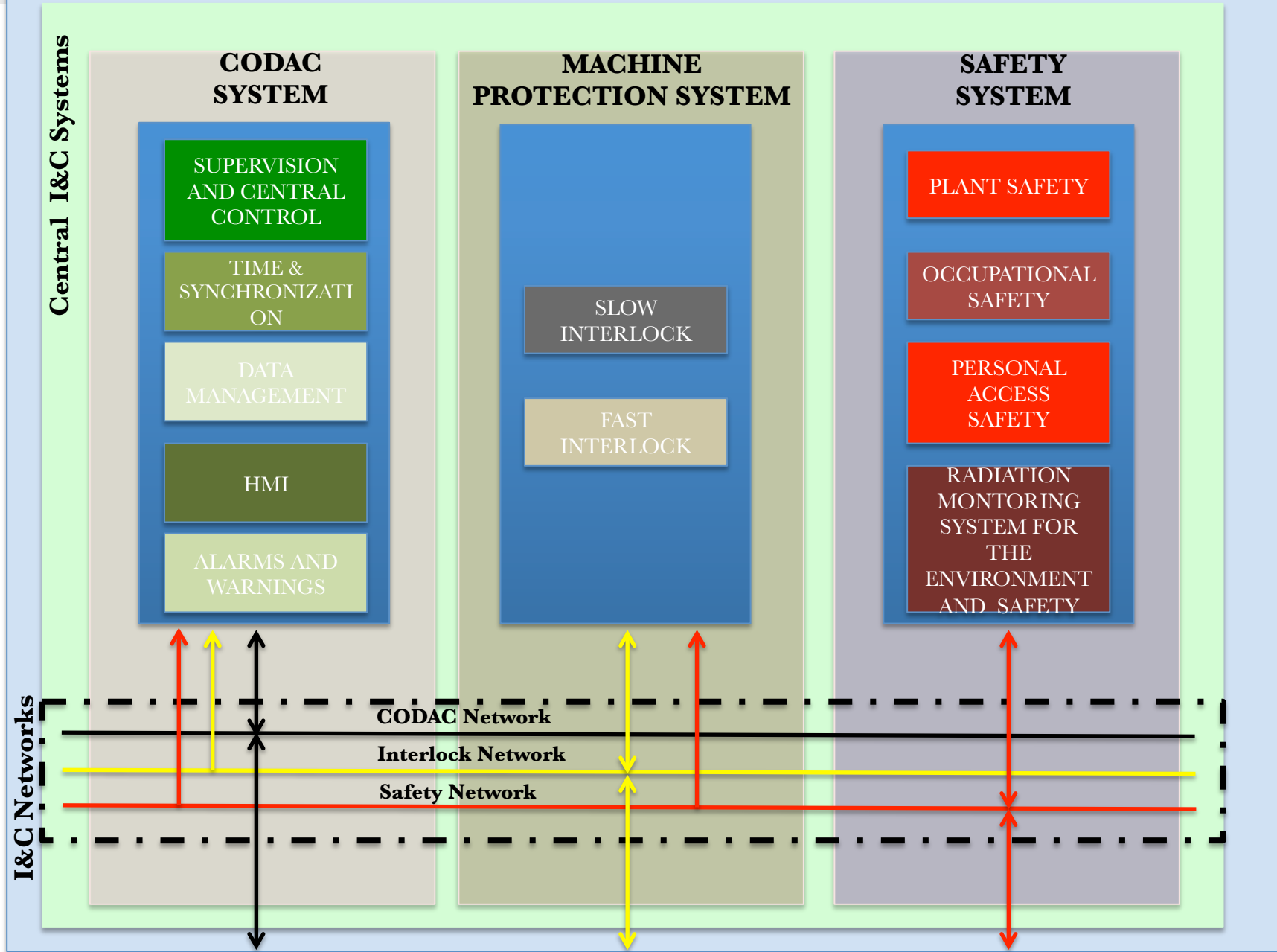
DONES I&C ARCHITECTURE

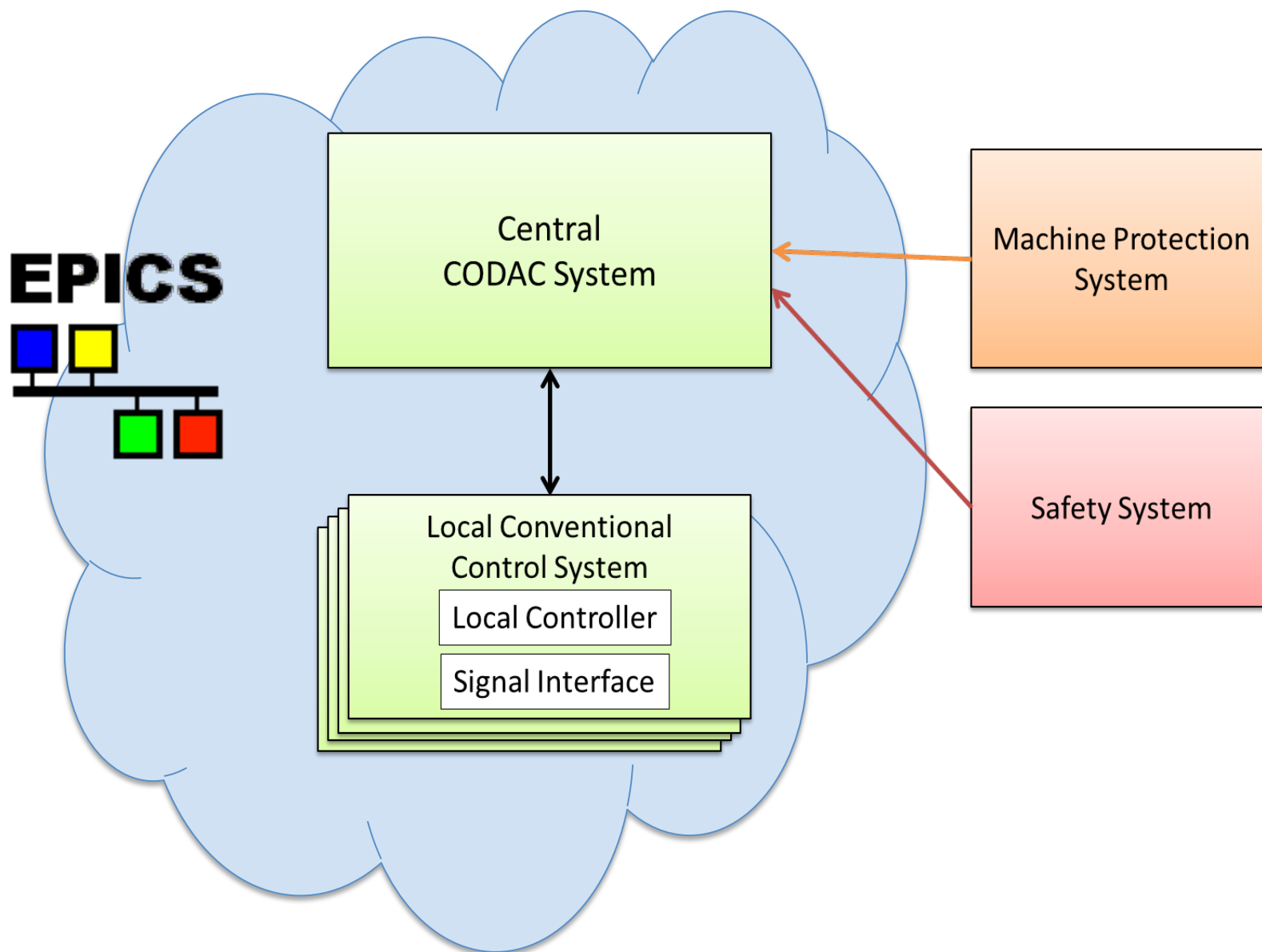




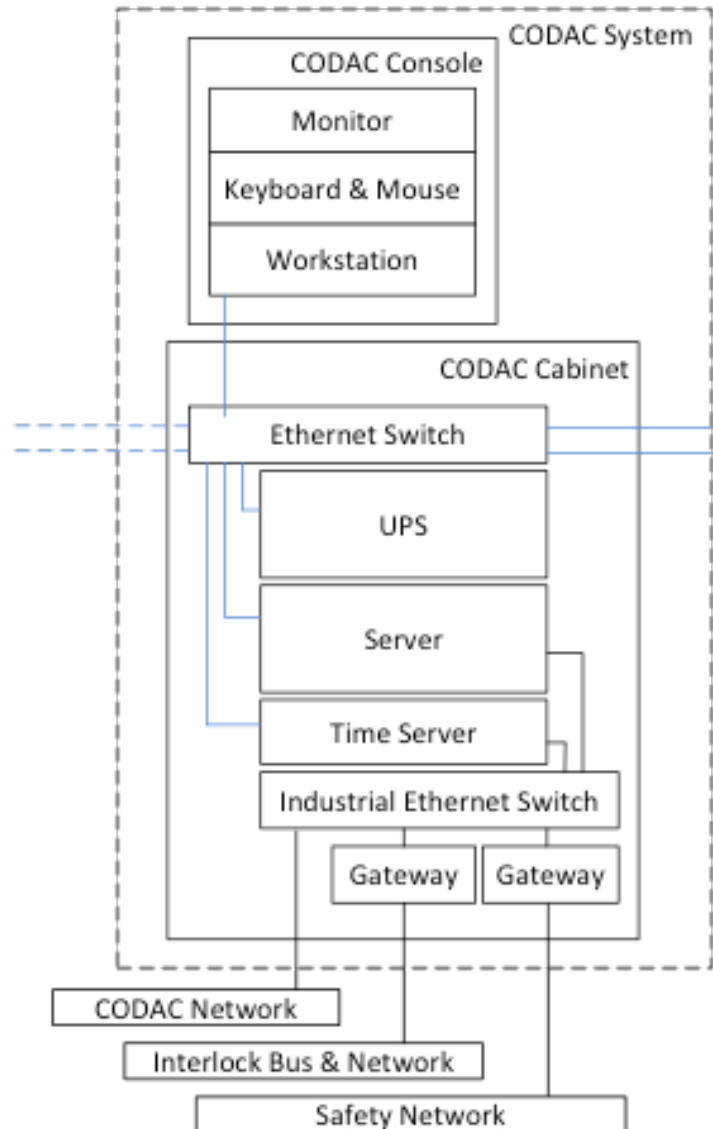
DONES I&C SYSTEMS

DONES I&C ARCHITECTURE

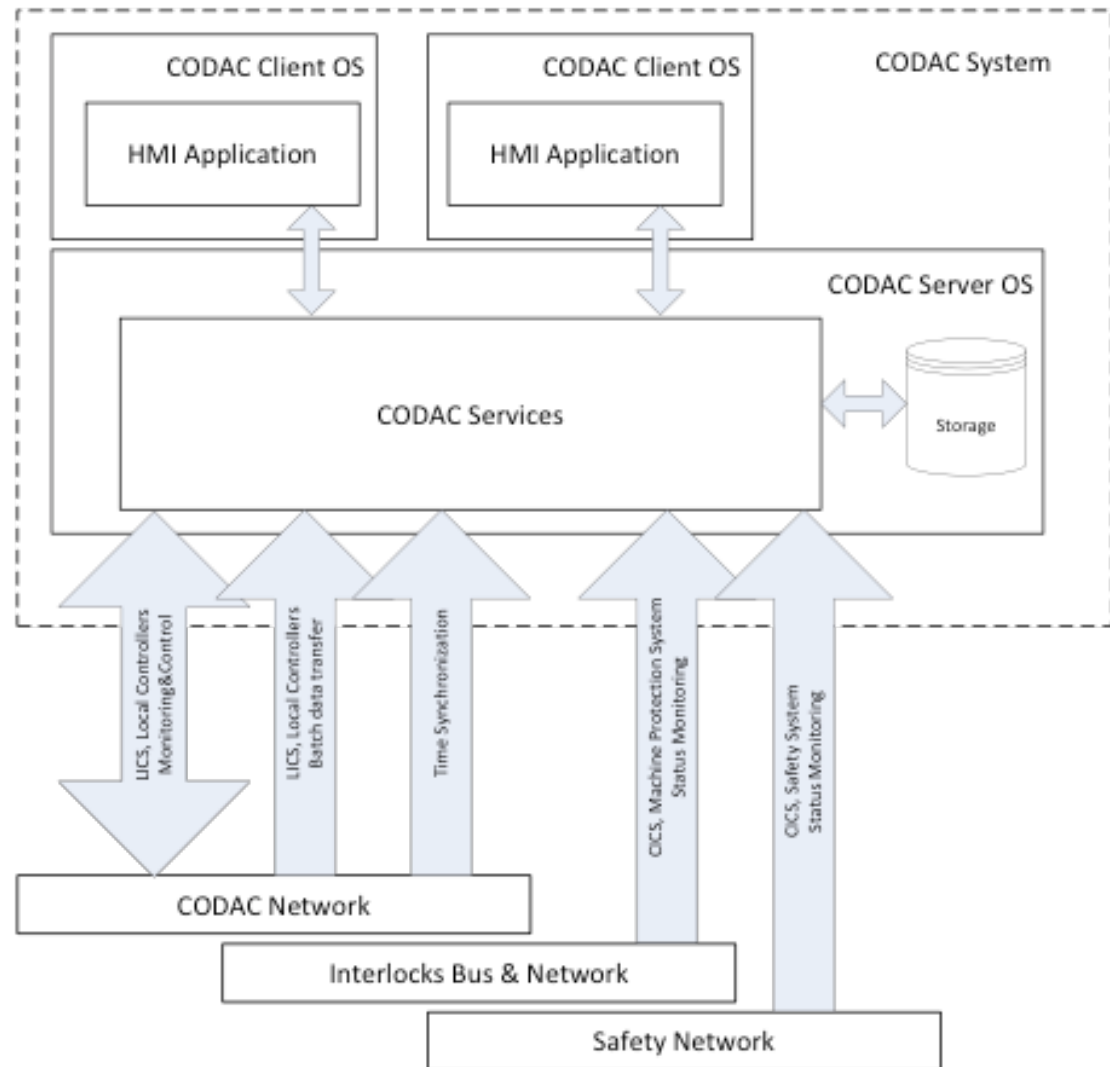




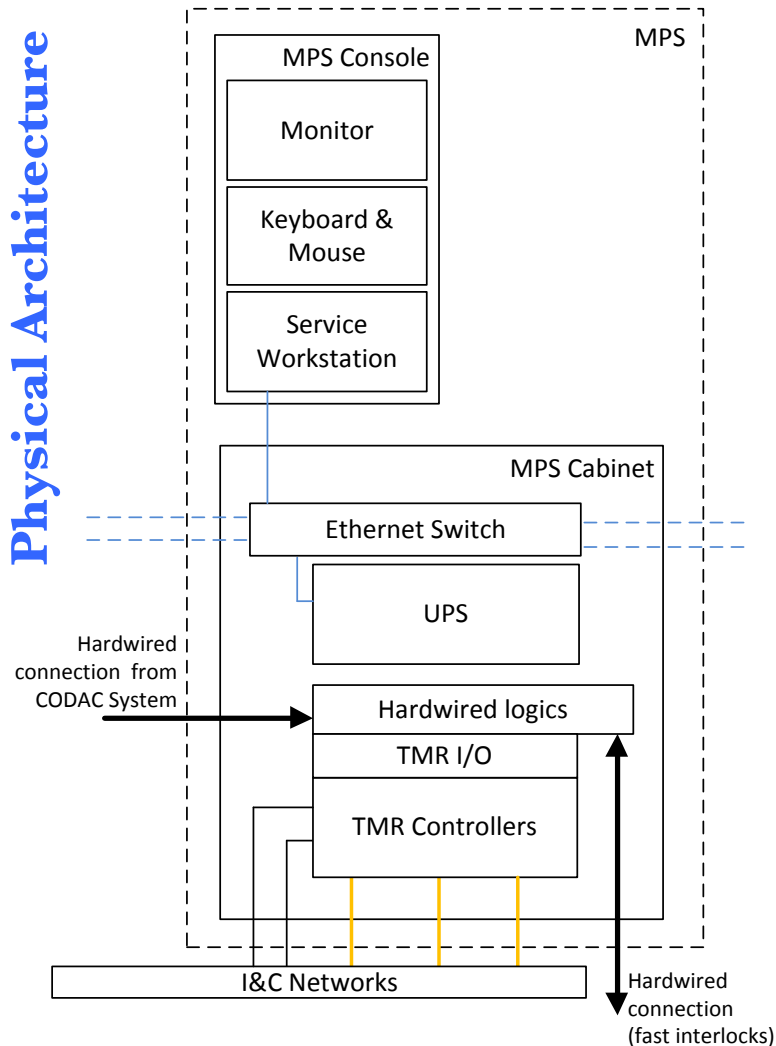
Physical Architecture



Software Architecture

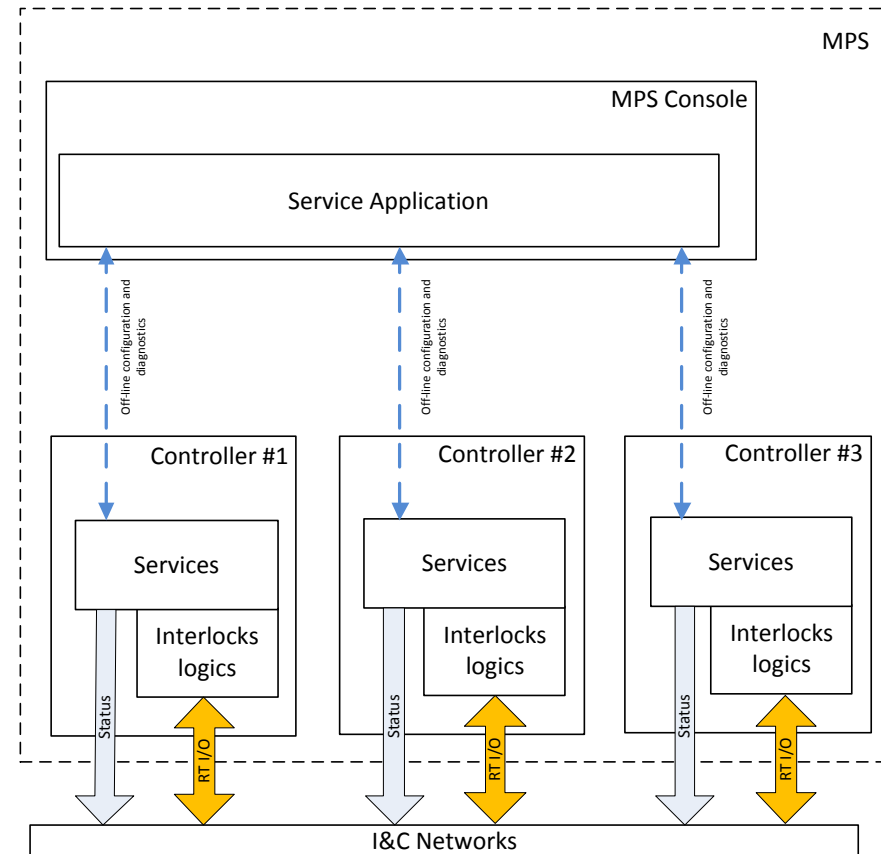


Physical Architecture



Three Modular Redundant (TMR) controller for slow interlocks
 Hardwired logics for fast interlocks
 Service workstation for configuration and management

Software Architecture

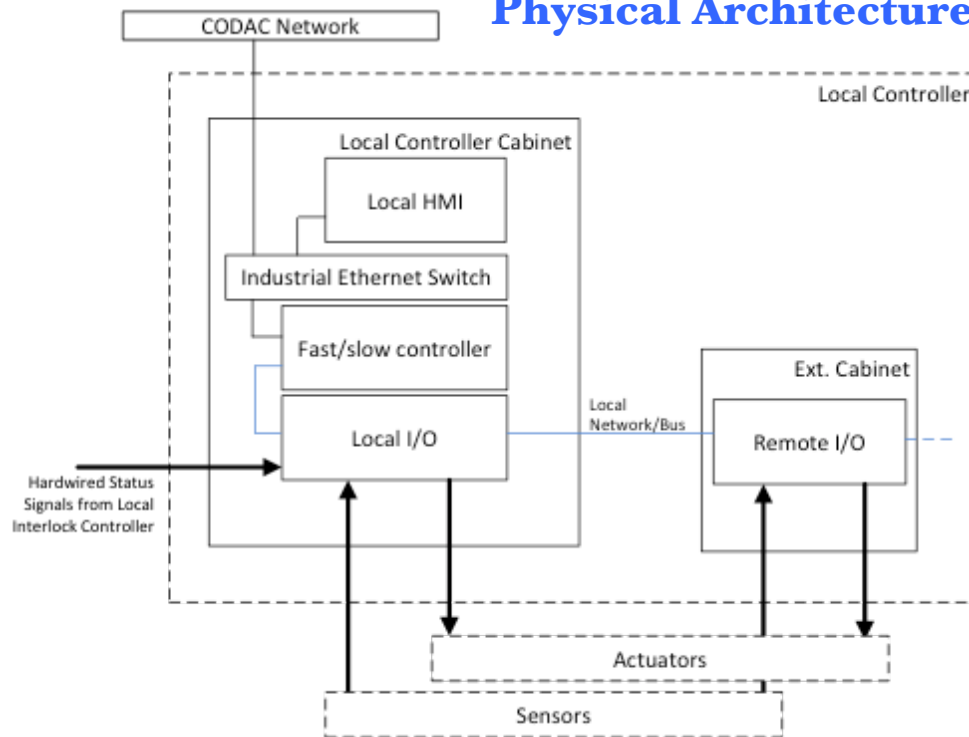


Three identical control logics running in parallel
 Voting system: logics 2oo3

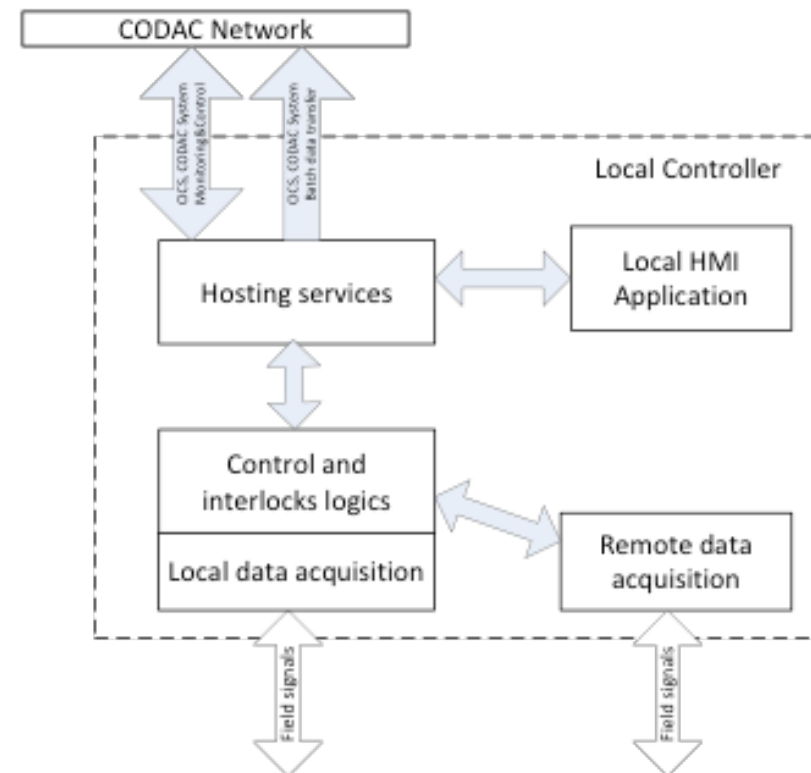
The typical Local Controller system consists of one **Local Controller Cabinet** and a set **Extension Cabinets**.

The Local Controller software have to provide the following operation:
 Field data acquisition and generation;
 Field data processing, control loops and soft interlocks execution;
 Data exchange with the CODAC Server;
 Local HMI.

Physical Architecture



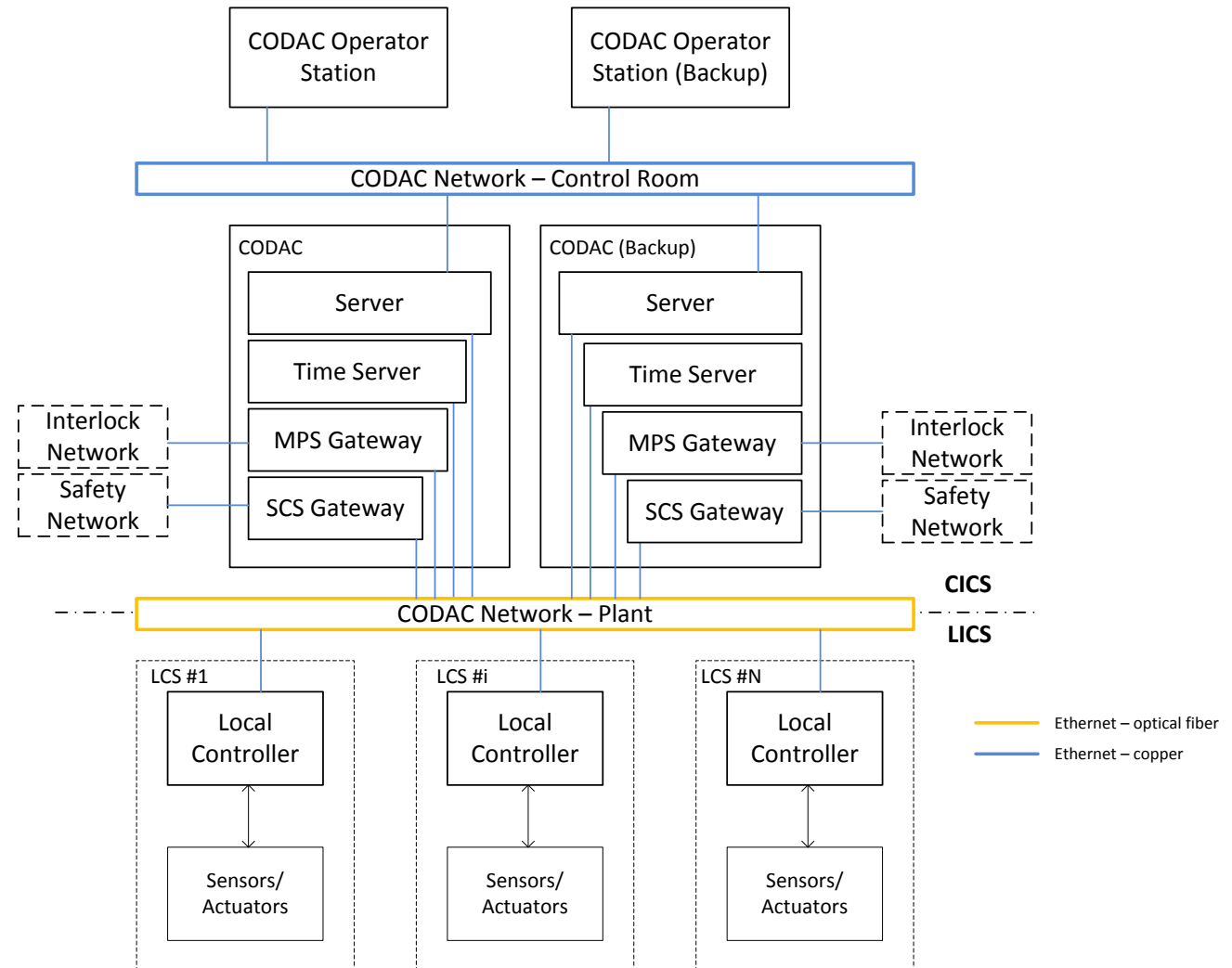
Software Architecture



Two layers for logical and physical segregation

Main requirements

- Gigabit Ethernet (10/100/1000)
- Ring-based redundant architecture
- Optical connection for plant section
- Copper for Control Room section



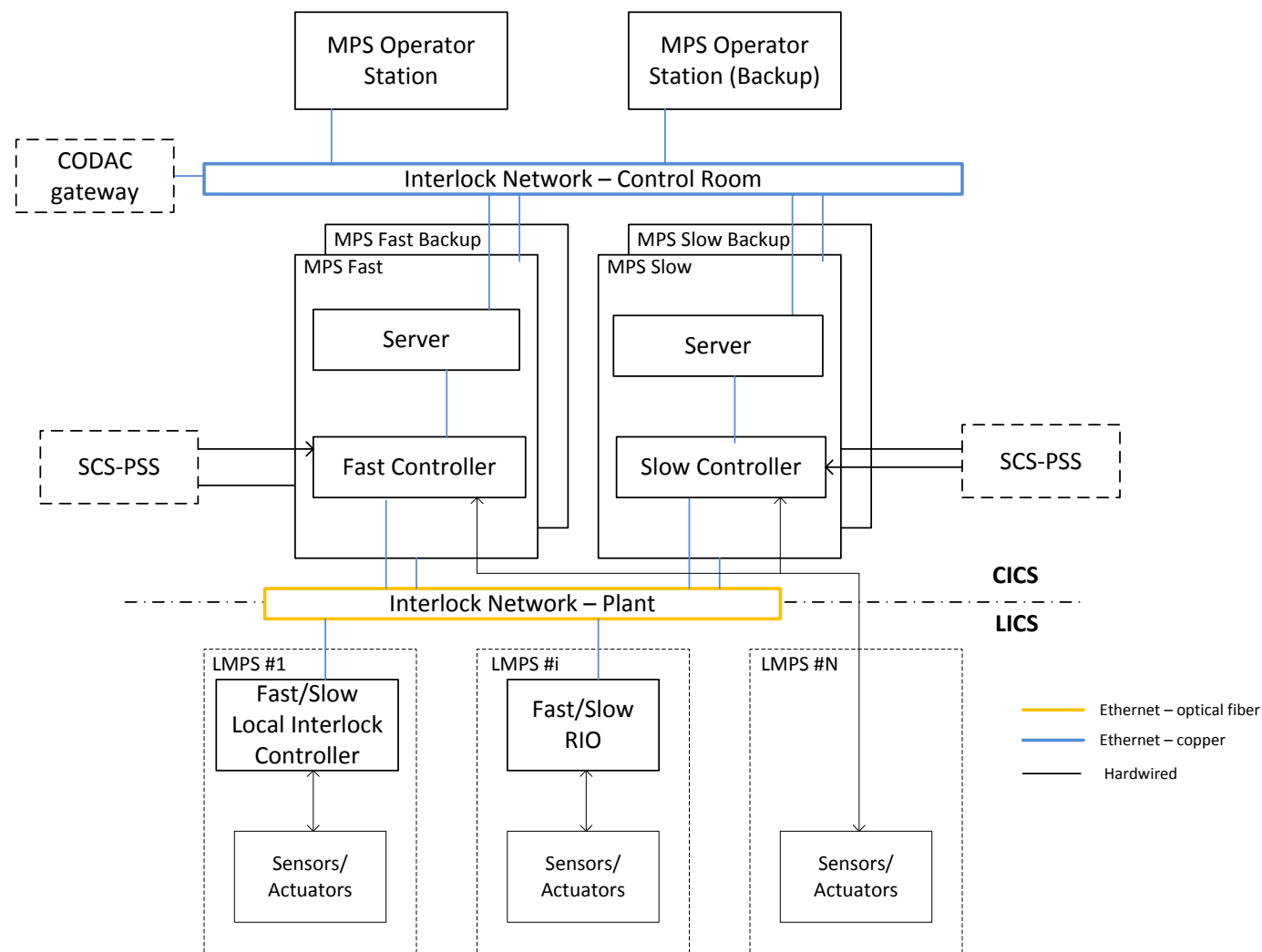
Two layers for logical and physical segregation

Main requirements

- Gigabit Ethernet (10/100/1000)
- ring-based redundant architecture
- Optical connection for plant section
- Copper for Control Room section
- Virtualization for sharing plant section between slow and fast data, assigning different QoS

Hardwired connections

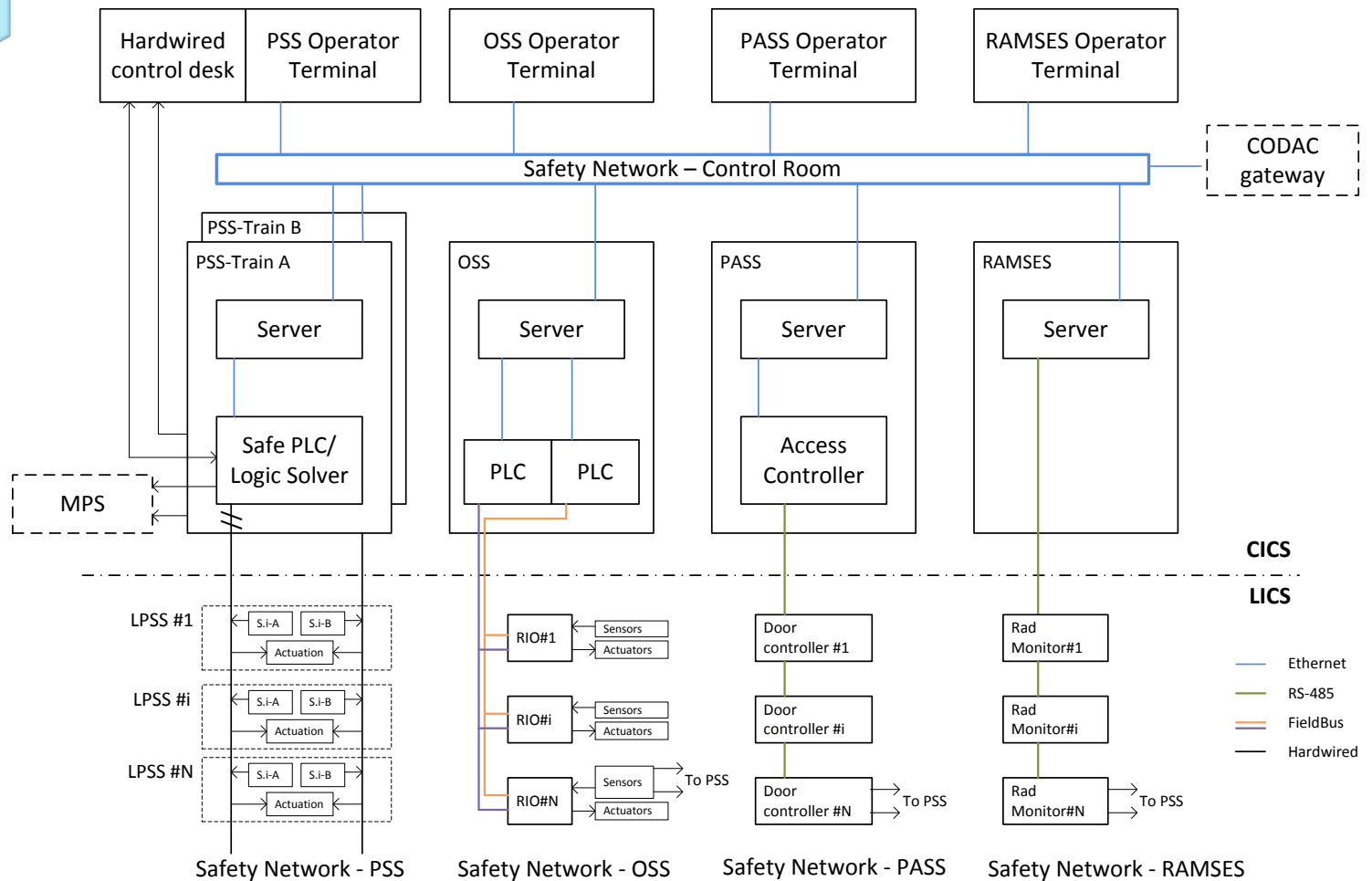
- LMPS and central fast controllers
- SCS and central fast controllers
- Central slow controller and central fast controller



SEPARATION VS INTEGRATION

Different SIC classification, but **access as a whole** from the operators:

- **lower part:** four separate “legs” (different for performance, configuration and physics).
- **upper part:** provides the seamless integration of the safety data to be accessed by the operator and by the CODAC gateway.



The **separation** between the different levels of the networks is always mediated by **servers** (separation layer between the operators and the safety controllers).

An **additional degree of separation** is created toward the interfacing CODAC system (not safety-classified), by means of the CODAC gateway.

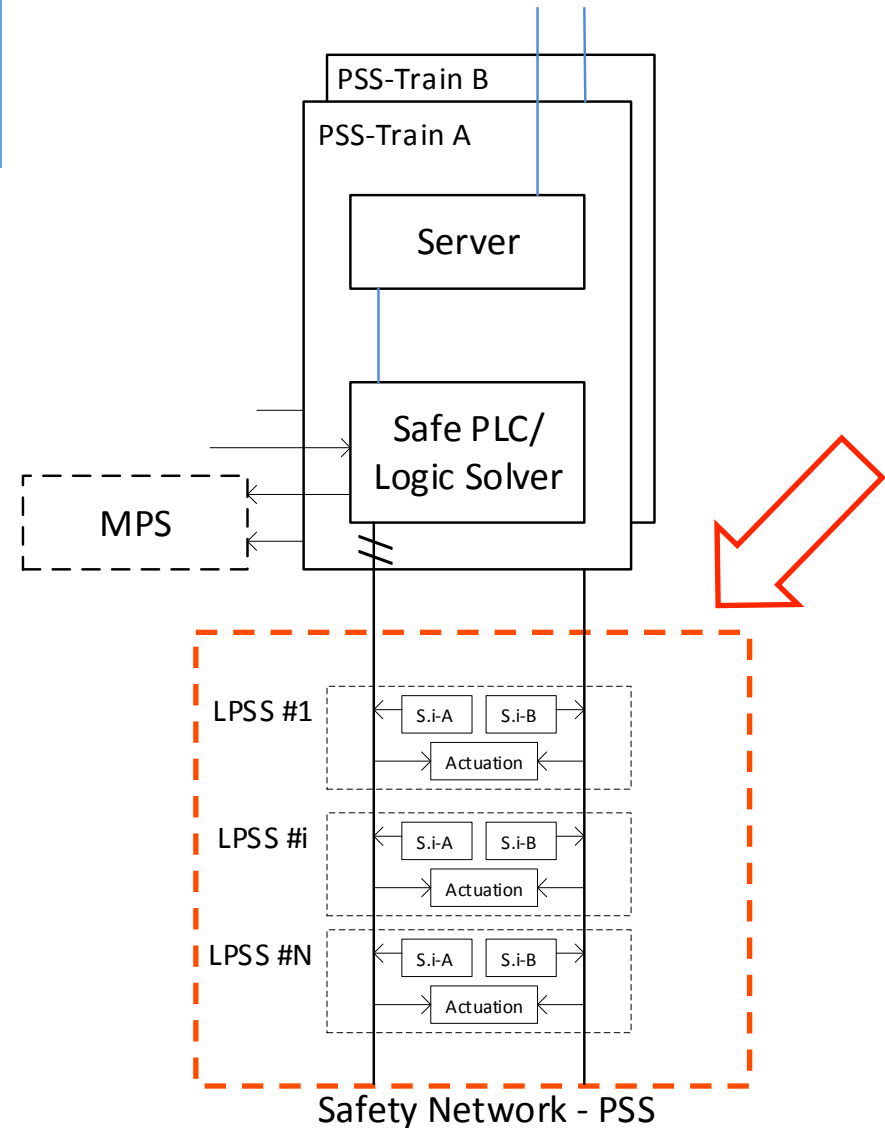
The **PSS** implements the safety functions: **two identical trains** collecting the inputs from the plant sensors (installed in different parts of the plant).

Input data also include signal coming from the other SCS sub-systems (**OSS, PASS, RAMSES**), as well as the signals generated from the **operator hardwired HMI**.

Each controller perform the safety logics in **independent** way and a **double voting** mechanism checks the elaboration results for discrepancies.

The design of the SN-PSS is strongly related to the assigned **SIC level**.

In this preliminary definition, it is assumed to use a direct cabling of the field devices.



- Design of the **Central** Instrumentation and Control Systems with its relationship with **Local** Instrumentation and Control Systems has been presented
- Status of the project is at a **preliminary phase** (the overall plant design is still ongoing)
- **Main components and networks** have been characterized
- No specific attention to **software/hardware solutions** at this stage

Some future work...

- Control **logics** in operational and emergency conditions (integration)
- **Safety** signals identification and **SIC** components design
- **Timing network** based on IEEE-1588 with three levels of accuracy
- Specific Safety Control System subsystems detailed design:
 - **Occupational Safety (OSS)**
 - **Personnel Access (PASS)**
 - **Environment Radiation Monitoring System (RAMSES)**